ON THE ESTIMATION OF MEAN WHEN POPULATION VARIANCE IS KNOWN

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SUMMARY

A class of estimators for population mean when the population variance is known has been suggested. It is shown that the optimum estimator in the class has a smallar bias as compared to estimators proposed earlier.

Keywords: Optimum estimator, mean square error, large sample approximations.

Introduction

Let y_1, y_2, \ldots, y_n be a random sample of size n from a population with unknown mean \overline{Y} and known variance σ^2 . Upadhyaya and Srivastava [2] proposed the estimator

$$\bar{Y}_1 = \bar{y} + \sigma^2/n\bar{y} \tag{1.1}$$

and obtained the bias and mean squared error (MSE) to order $O(n^{-2})$ as

Bias
$$(\overline{Y}_1) = (\sigma^2/n\overline{Y}) (1 + \sigma^2/n\overline{Y}^2)$$
 (1,2)

and MSE
$$(\bar{y}_1) = (\sigma^2/n) (1 - \sigma^2/n\bar{Y}^2)$$
 (1.3)

Upadhyaya and Singh [1] proposed an equally efficient estimator

$$\bar{y}_2 = \bar{y} + \sigma^2 \ \overline{Y}/n\bar{y}(^2 + \sigma^2) \tag{1.4}$$

but with smaller bias to order $O(n^{-2})$ as

$$Bias (p_2) = \sigma^2/n\overline{Y}$$
 (1.5)

The purpose of this paper is to consider a class of estimators of the mean when population variance is known. The large sample approximations have also been investigated.

2. Proposed Class of Estimators

Assuming the population variance σ^2 to be known, we consider the class of estimators for the mean \bar{Y} as

$$\bar{y}_2 = \bar{y} + K\sigma^2 \,\bar{y}\delta - \sigma^2/n\bar{y} \tag{2.1}$$

where $\delta = (n\mathfrak{P}^2 + \sigma^3)^{-1}$ and K is the characterizing scalar to be chosen suitably.

The bias, MSE and Kopt. for minimum MSE are

Bias
$$(\bar{y}_3) = K\sigma^2 E(\bar{y}\delta) - \sigma^2 E(n\bar{y})^{-1}$$
 (2.2)

MSE
$$(\bar{y}_3) = E(\bar{y}_3 - \bar{Y})^3 + K^2 \sigma^4 E(\bar{y} \delta)^2 + \sigma^4 E(n^2 \bar{y}^2)^{-1} + 2K \sigma^2 E(\bar{Y}^2 \delta) - 2K \sigma^2 \bar{Y} E(\bar{y} \delta) - 2K \sigma^4 n^{-1} E(\delta) + 2\sigma^3 \bar{Y} E(n\bar{y})^{-1} - 2\sigma^2 n^{-1}$$
 (2.3)

and
$$K_{\text{opt.}} = [\overline{Y} E(\bar{y}\delta) + \sigma^2 n^{-1} E(\delta) - E\bar{y}^2\delta)] / [\sigma^2 E(\bar{y}\delta)^2]$$
 (2.4)

The expectations involved in these expressions are mathematically intractable. We, therefore, resort to derive the large sample approximations.

3. Large Sample Approximations

We write

$$\overline{\nu} = \overline{Y} + \varepsilon$$

where ε is of the order $O(n^{-1/2})$ with $E(\varepsilon) = 0$ and $E(\varepsilon^2) = \sigma^2/n$. Choosing n large enough so that $|\varepsilon| |\overline{Y}| < 1$, we may easily get the expectations by retaining terms of order $O(n^{-2})$ as

$$E(n\bar{y})^{-1} = (1 + \sigma^2/n\bar{Y}^2)/n\bar{Y}, E(n^2\bar{y}^2)^{-1} = (n^2\bar{Y}^2)^{-1}$$

$$E(\delta) = (1 + 2\sigma^2/n\bar{Y}^2)/n\bar{Y}^2, E(\bar{y}\delta) = (n\bar{Y})^{-1}$$
(3.1)

and
$$E(\bar{p}\delta)^2 = (n^2 \bar{Y}^2)^{-1}$$
 and $E(\bar{p}^2\delta) = 1 - \sigma^2/n\bar{Y}^2/n$

From (2.2), (2.3), (2.4) and (3.1) we get (upto terms of order $O(n^{-2})$)

Bias
$$(\bar{y}_3) = \sigma^2 (K - 1 - \sigma^2/n\bar{Y}^2)/n\bar{Y}$$
 (3.2)

MSE
$$(\bar{y}_3) = \sigma^2 [1 + (K-1) (K-3) \sigma^2 / n \bar{Y}^2] / n$$
 (3.3)

and
$$K_{\text{opt}} = 2$$
. (3.4)

4. Comparison

For Kopt., the estimator y_8 , its bias and MSE become

$$\overline{y_3} = \bar{y} + \sigma^2 \, \bar{y} \, (1 - \sigma^2/n\bar{y}^2)/(n\bar{y}^3 + \sigma^2) \tag{4.1}$$

Bias
$$(\bar{y}_3) = (\sigma^2/nY)(1 - \sigma^2/nY^2)$$
 (4.2)

and MES
$$(\bar{y}_3) = (\sigma^2/n) (1 - \sigma^2/n \bar{Y}^2)$$
 (4.3)

From (1.2), (1.5) and (4.2), we have Bias $(\overline{Y}_3) < \text{Bias }(\overline{Y}_2) < \text{Bias }(\overline{Y}_1)$ upto $O(n^{-3})$. And all three estimators have equal MSE. Therefore, the estimator \overline{y}_3 is an improvement over \overline{y}_3 and \overline{y}_1 .

REFEREECES

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